



DEEP LEARNING

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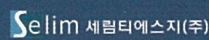
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올포랜드



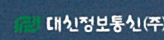
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Cobotsys



RIAN



대신정보통신(주)



SK broadband



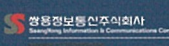
아이씨웨이(주)



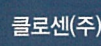
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클로센(주)



승화

An Embedded Compact Transformer Vision System for Real-Time Health classification during Seedling Transplanting



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Introduction

Necessity

Seedling transplanting is an important step in plant production to transplant seedlings into low-density trays at specific growth stage. Simultaneously, it is necessary to decide and select the growth status of seedlings in order to improve production quantity and quality.

Objective

Propose a compact Transformer-based vision system for real-time health classification of seedlings during the transplantation process. The algorithm is designed to be simple and compact, making it suitable for use on embedded devices with limited computational resources.



< Seedling transplanting >

Seedling culture and data collection



< Seedling cultivation environment >



< Experimental seedling cultivation >



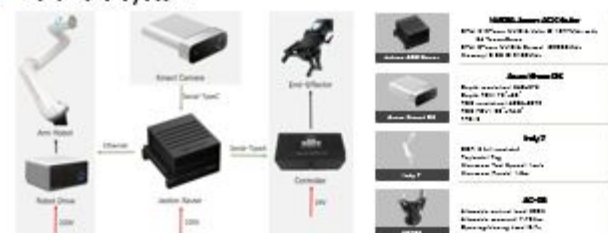
< Transplanting software interface >



< Transplanting operation scenario >

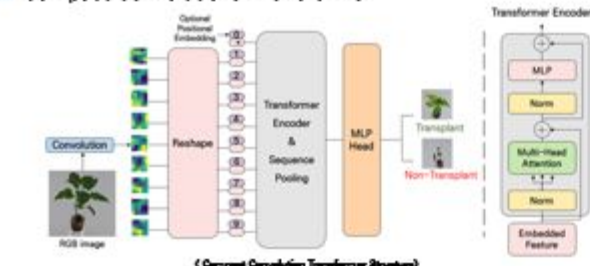
Materials & Methods

Hardware system



< Hardware system configuration >

Compact Convolutional Transformer



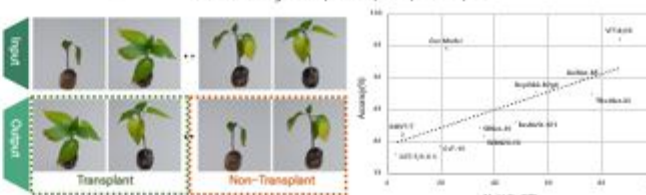
(Compact Convolutional Transformer Structure)

- Based on CNN-Transformer model is proposed, including two convolutional modules, seven Transformer modules, sequence pools and MLP outputs.
- The attention mechanism of transformer module and sequence pool is used to map the output to a single category index and assign data sequences according to weights, which improves the efficiency and accuracy of feature extraction.

Experiment and Results



< Model training results (Precision, Recall, F1-Score) >



< Part of the classification results >

< The Performance of Different Algorithms >

- The dataset consists of 604 paprika image data divided into training, validation and test according to the ratio of 6:2:2.
- The training parameters : Batch size: 5, Learning Rate: 0.0005, Iteration: 200.
- The results were Accuracy: 94.5%, Recall: 97.1%, Precision: 94.9%, F1-score: 95.9%, and FPS: 7.6.

Conclusions

- Reduce model size 2-4 times compared to SOTA while maintaining accuracy.
- Select embedded device as the computing platform to reduce costs while increasing deployment flexibility.

References

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- Fu, W.; Gao, J.; Zhao, C.; Jiang, K.; Zheng, W.; Tian, Y. Detection Method and Experimental Research of Leafy Vegetable Seedlings Transplanting Based on a Machine Vision. *Agronomy* 2022, 12, 2899.

Acknowledgements

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